

Istituto Nazionale di Fisica Nucleare SEZIONE DI TORINO



The TOP counter of Belle II: status and first results

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INFN – Sezione di Torino

Outline





 \rightarrow Basic features of the Belle II Time-Of-Propagation counter

→ The first PID results

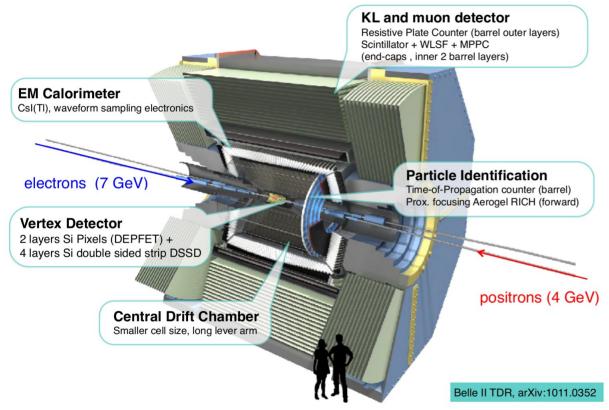
→ Understanding the first PID results

Part I. The TOP detector (and Belle II)

The Belle II detector





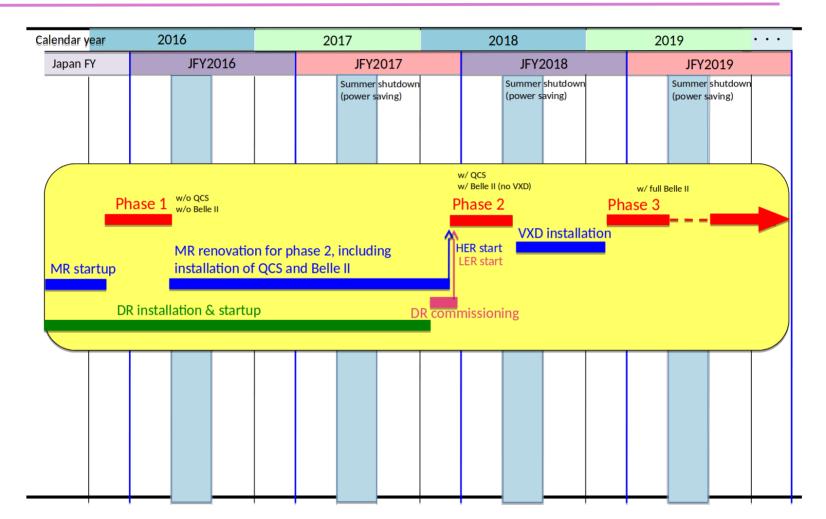


- \rightarrow CP violation
- → Every sub-detector provides PID information
 - \rightarrow dE/dx from Drift Chamber and Vertex detector
 - → Cherenkov signal from TOP and ARICH
 - → Shower shapes from the calorimeter
 - \rightarrow Penetration depth from the muon system

The Belle II experiment: a timeline







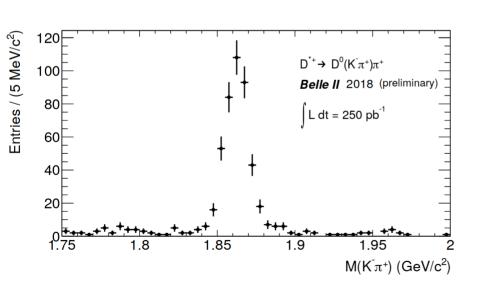
The first Belle II results

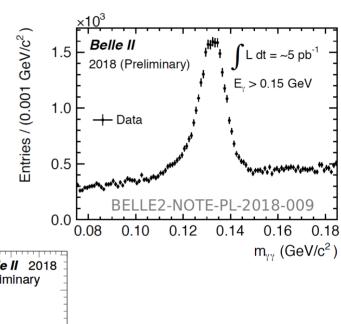


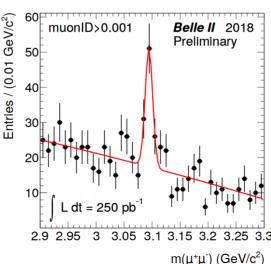


Phase II lasted from April 26th to July 17th

- ightarrow 0.5 fb⁻¹ of collisions at Y(4S)
- $ightarrow 0.55 imes 10^{34} \ cm^{-2} s^{-1} \ maximum \ luminosity$
- ightarrow Very extensive background and accelerator studies







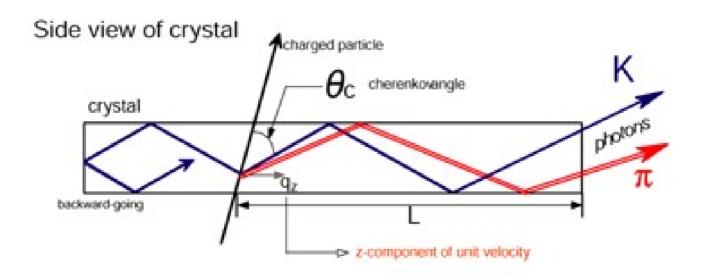
The TOP counter principle





The TOP is a "DIRC in the time domain"

- ightarrow Cherenkov light trapped and propagated to the readout in a wide bar of fused silica
- ightarrow The Cherenkov angle is measured by the **time of propagation** rather than the ring image on the PMT surface



The TOP counter at Belle II

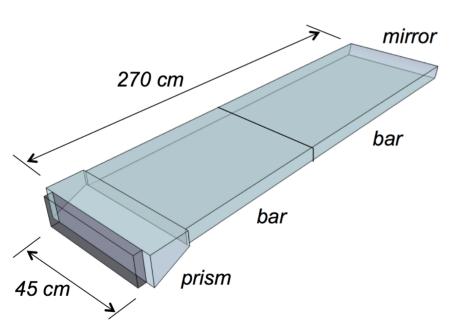


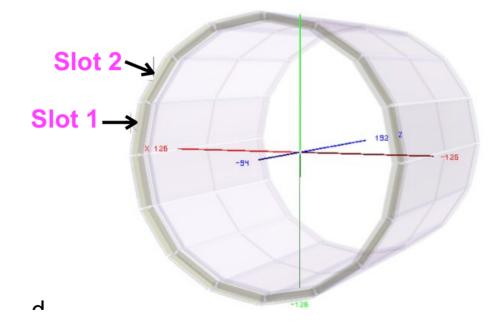


TOP implementation in Belle II:

- ightarrow 16 modules (or slots) arranged around the interaction point
- ightarrow Each module is made of two identical bars of fused silica glued together
- → Backward side: expansion prism, PMTs and readout

→ Forward side: spherical mirror

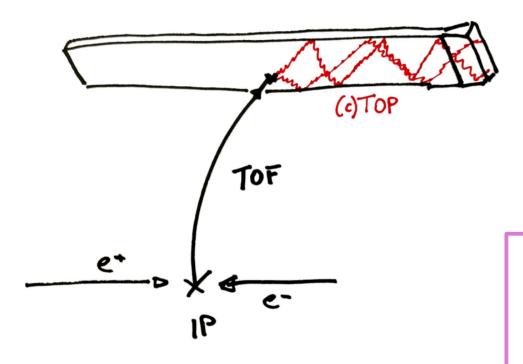




What does the TOP measure?







At a collider machine, we can combine the **ToF** and the **Cherenkov angle** in one single measurement

Key ingredients:

- \rightarrow Impact point on the detector
- \rightarrow Single p.e. time resolution (PMT + readout only)< 100 ps
- \rightarrow RF locking resolution < 10 ps

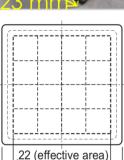
Readout: The PMTs





The single photoelectron time resolution is the key parameter for the TOP Our target is $\sigma(1 \text{ p.e.}) < 100 \text{ ps}$

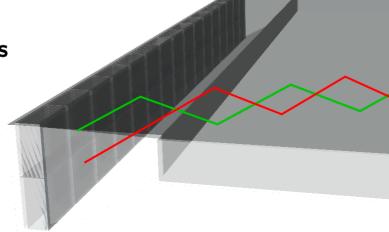




27.5 mm

Hamamatsu MCP-MPTs

- ightarrow (1 x 1) in, ~70% active area
- \rightarrow NaKSbCs photocathode; QE \geq 24% (28% on average) at 380 nm
- ightarrow 55% collection efficiency
- ightarrow Gain $= 10^5 10^6$
- \rightarrow Transient time spread < 40 ps



Readout: The electronics





TOP front end electronics is based on the *IRSX chip* developed by Hawaii University arXiv:1804.10782

Scope-on-a-chip

- \rightarrow 8 channel waveform digitizer
- → 500 MHz Bandwidth
- \rightarrow 2.7 GSa/s
- ightarrow 11.6 µs storage buffer
- → Full waveform output

Controlled by Xilinx Zinq FPGAs

- → Online pedestal subtraction
- → Online waveform analysis







See Maeda-san's poster for more information!

Part II.

First physics results

TOP performances in Phase II





TOP in phase II:

- \rightarrow Uptime > 90%
- \rightarrow Active channels = 97.5%
- → Trigger capabilities verified*
- \rightarrow Preliminary calibrations
- → First evidences of particle identification capabilities



^{*} the TOP does not provide a trigger, but a T0 determination

TOP impact on physics





The PID in Belle II is managed using only likelihood values

- ightarrow Each sub-detector provide a set of likelihood values for 6 mass hypotheses (from electron to deuteron)
- → Likelihoods are then combined

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Basic figure for two particle separation:

Log-Likelihood difference

A particle is identified as x rather than y if LL(x) > LL(y)

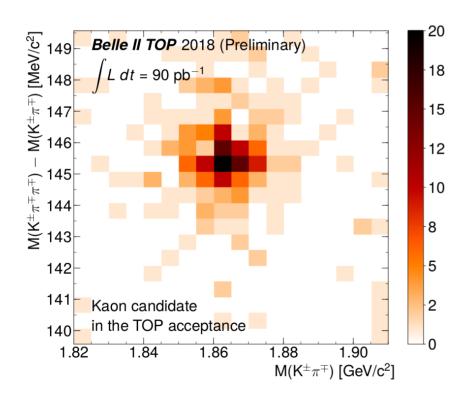
Visualizing the Cherenkov rings

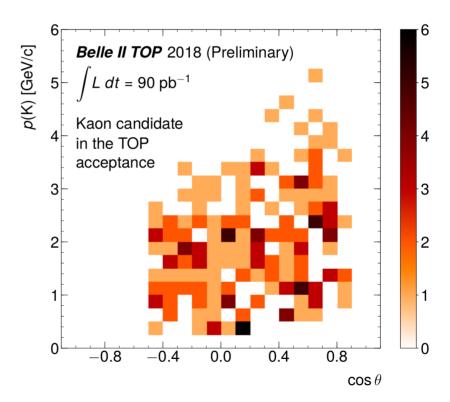




Compare the expected PDF with the observed hits for a known particle species

\rightarrow Pure Kaon sample from D* \rightarrow D $^{0}\pi \rightarrow$ K $\pi\pi$

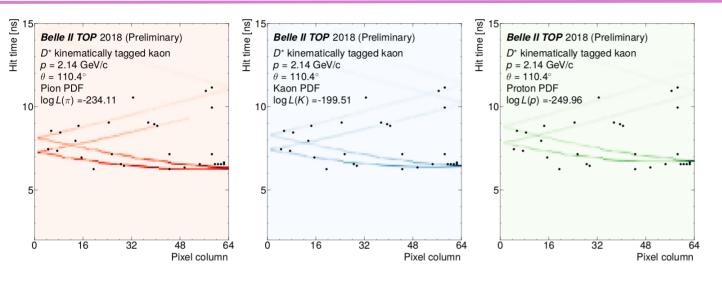




Visualizing the Cherenkov rings



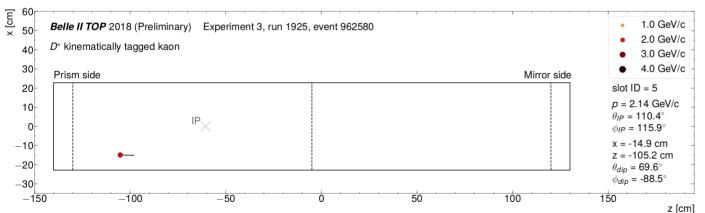






Little room for the Cherenkov cone to open up

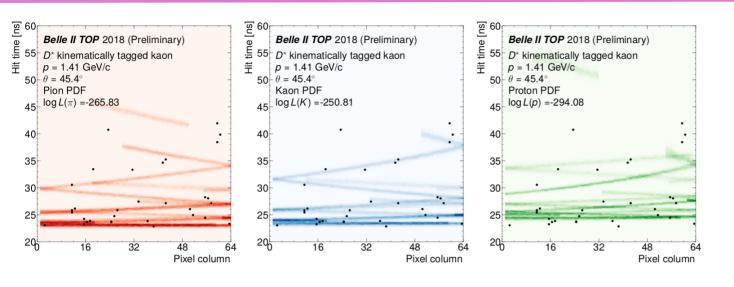
ID is dominated by the PDF shift (i.e. ToF) rather than the shape difference



Visualizing the Cherenkov rings

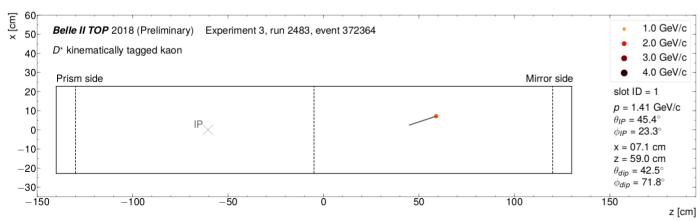






1.41 GeV mirror-facing event

ID is dominated by the PDF shape (i.e. Cherenkov ring) rather than the global offset



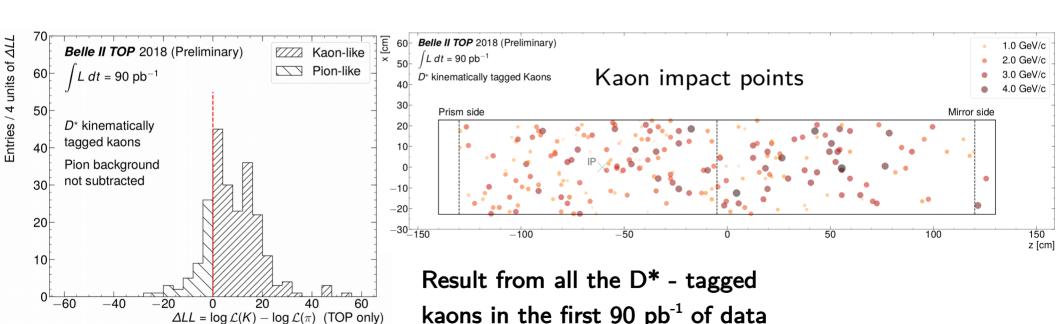
From event displays to likelihoods





The PID in Belle II is managed using only likelihood values

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- → Likelihoods are then combined

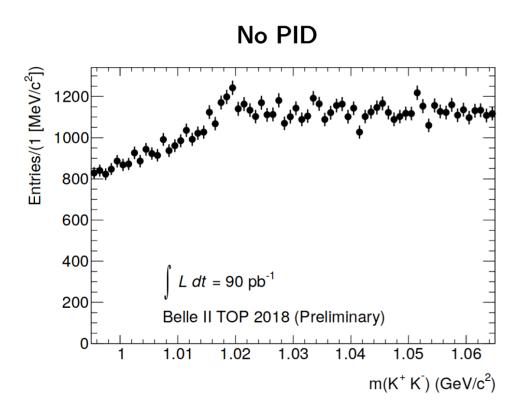


TOP impact on physics: $K-\pi$ separation





 $\phi \to K^+K^-$ with both the tracks in the TOP acceptance

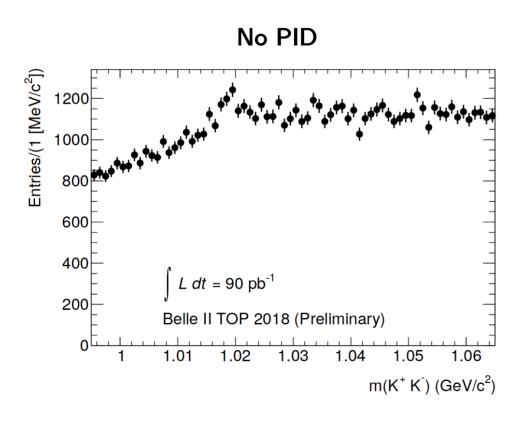


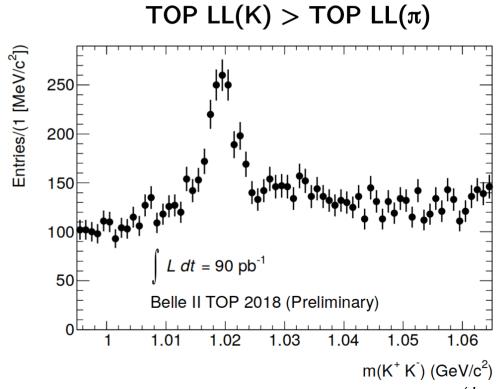
TOP impact on physics: $K-\pi$ separation





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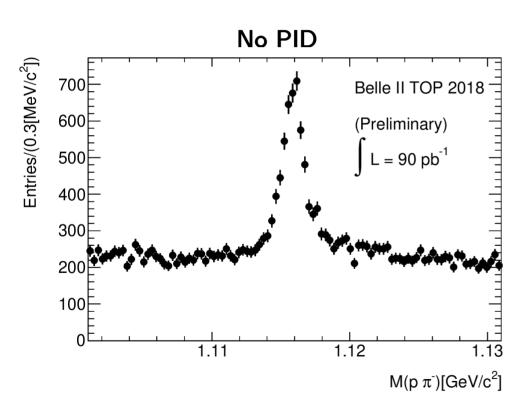


TOP impact on physics: $p-\pi$ separation





$\Lambda \to p\pi$ with the **proton candidate** in the TOP acceptance

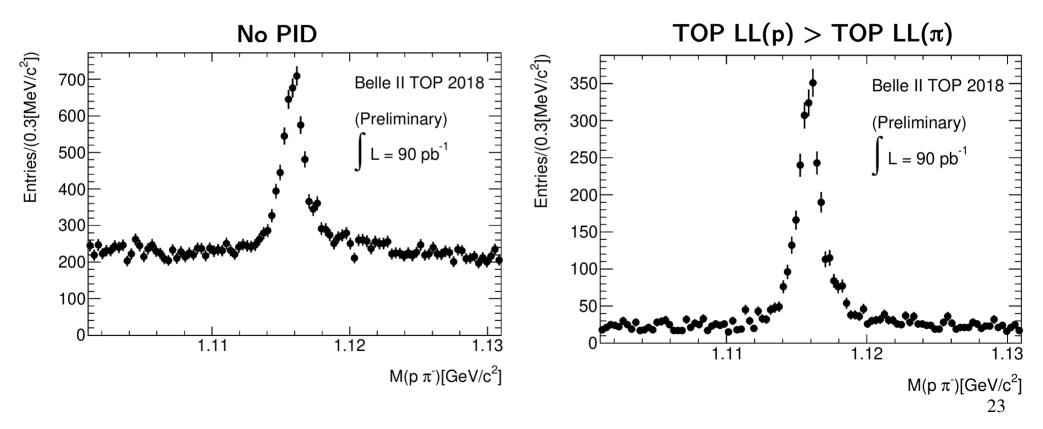


TOP impact on physics: $p-\pi$ separation





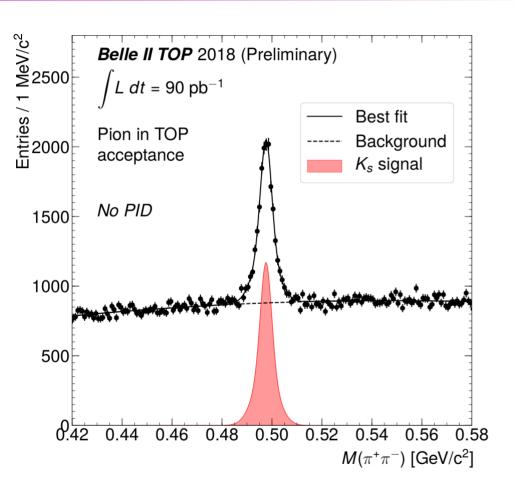
$\Lambda \to p\pi$ with the **proton candidate** in the TOP acceptance



Quantitative estimations: $K_{s} \rightarrow \pi\pi$







Large sample of pions tagged by the $K_{\underline{\ }} \to \pi\pi$ decay

- ightarrow Test of both identification efficiency and mis-identification probability
- → Measure the Ks yield when requiring, on one of the two pions:

$$LL(\pi) > LL(K)$$

$$LL(K) > LL(\pi)$$

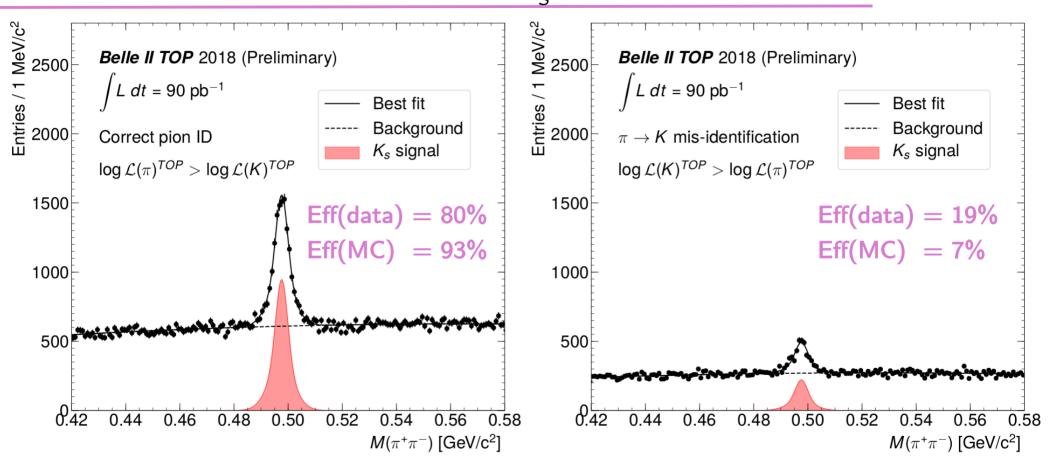
$$LL(p) > LL(\pi)$$

$$LL(e) > LL(\pi)$$

Quantitative estimations: $K_{\varsigma} \rightarrow \pi\pi$



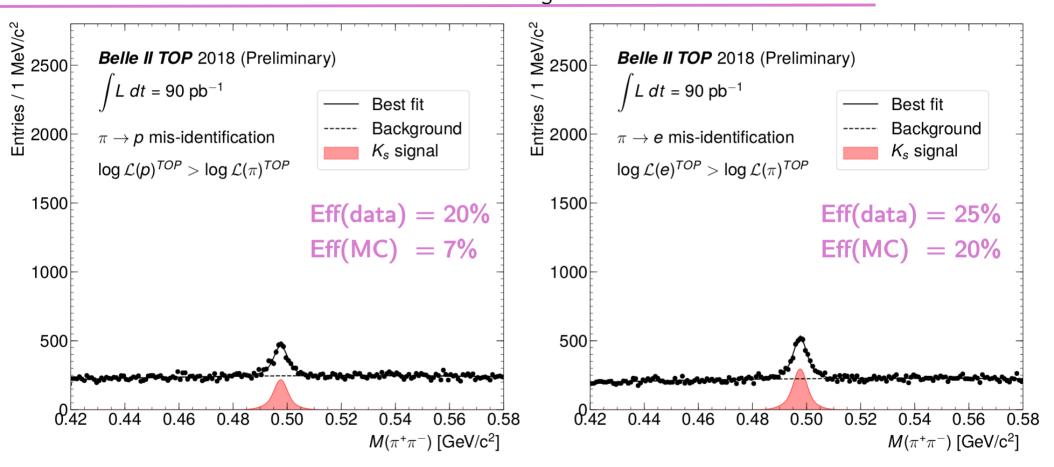




Quantitative estimations: $K_{\varsigma} \rightarrow \pi\pi$







Understanding the performances

Part III.

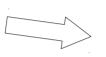
TOP Calibration





Most of the TOP calibration is time calibration

IRSX sampling linearity (electronic pulses)



Synchronization of the channels within one module (laser flashes)

Synchronization of the whole detector with the radiofrequency clock (di-muons)

Geometrical alignment (di-muons)

Synchronization of the modules within each other (di-muons or cosmics)

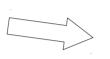
TOP Calibration



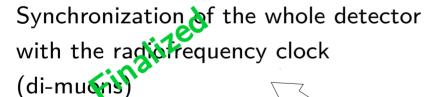


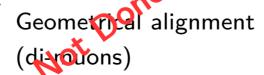
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Synchronization of the channels within one module (laser flashes)





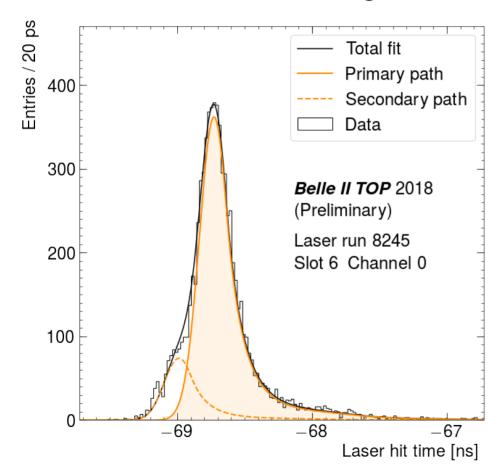
Synchronization of the modules within each other (di-muchs or cosmics)

Single channel time resolution



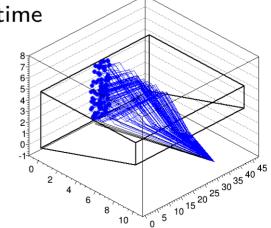


The time resolution on the single channel is estimated using laser flashes



Due to the reflection inside the expansion prism, multiple paths can lead to the same pixel.

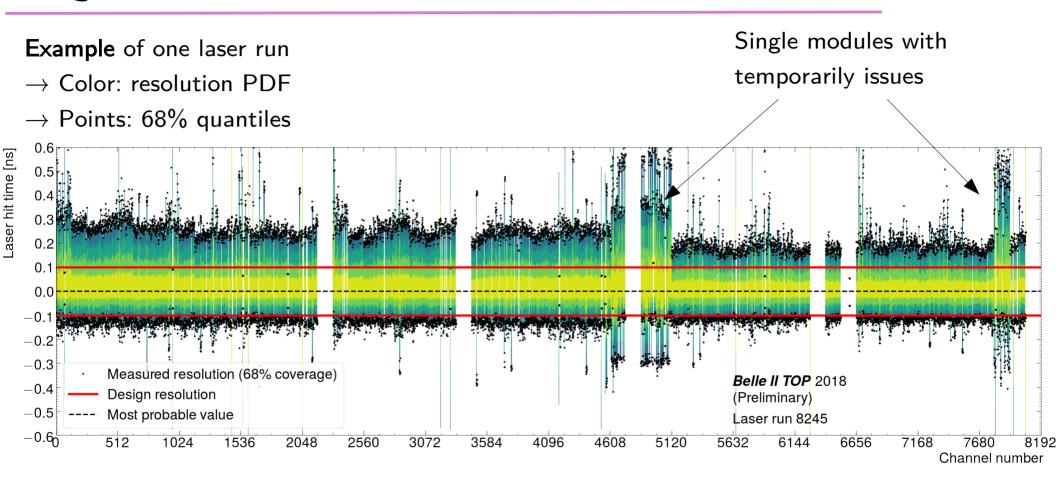
Each path is fitted with a crystal ball PDF for reproduce the tails in the PMT response time



Single channel time resolution







Note: laser and laser-related jitters are **not** deconvolved

TOP synchronization



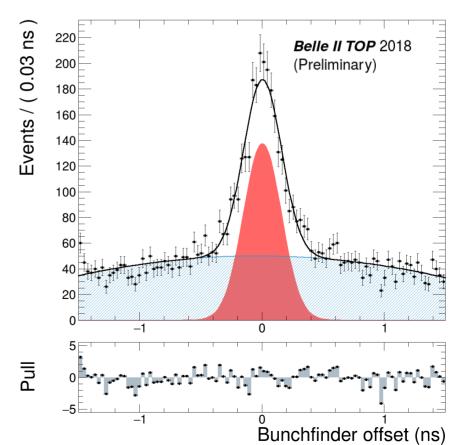


The TOP sampling clock is locked to the accelerator radio-frequency clock (RF clock)

 \rightarrow Any offset between the two will result in a mis-reconstruction of the PDFs

Most probable collision time

- → reconstructed back-fitting the higher momentum tracks in the event
- \rightarrow If calibrations are correct, it will match with a tick of the RF clock
- \rightarrow Resolution on data: 150 ps (bunch crossing: 2 ns)

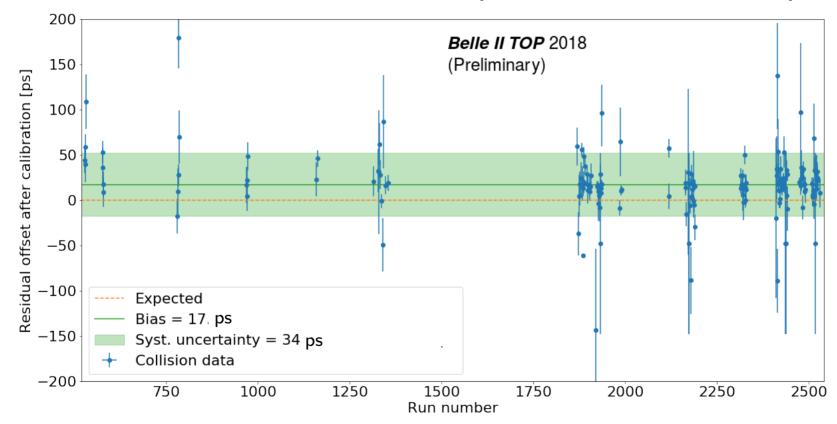


TOP synchronization





Bunch finder residual offset after the calibrations (RF synchronization precision)



ightarrow Synchronization with the RF is still not optimal

What's missing





Where can we improve the TOP performances?

1) Electronics

- \rightarrow 10-20% firmware inefficiency (partially solved)
- → ASICS parameters not optimized
- \rightarrow Template fit
- → Amplitude and gain corrections

2) Tracking

→ Any improvement in the tracking will improve the TOP PID

3) Calibrations and time resolution

- → Affected by tracking and electronics performances
- → Still statistically limited!

Conclusions



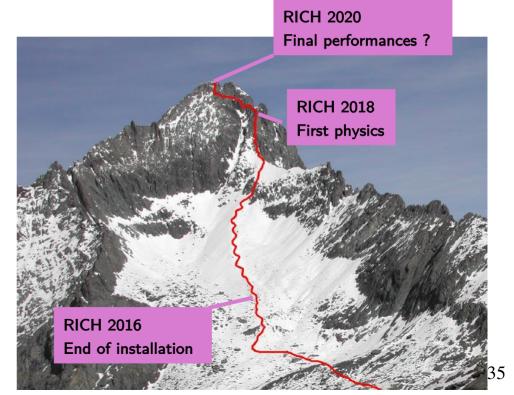


The Belle II experiment has successfully concluded the phase II pilot run:

- \rightarrow The TOP is working
- ightarrow The PID performances are still ~10% worst than in the MC

Still lot of work to be done!

- → Preliminary tuning of the electronics
- → Preliminary calibrations



Backup

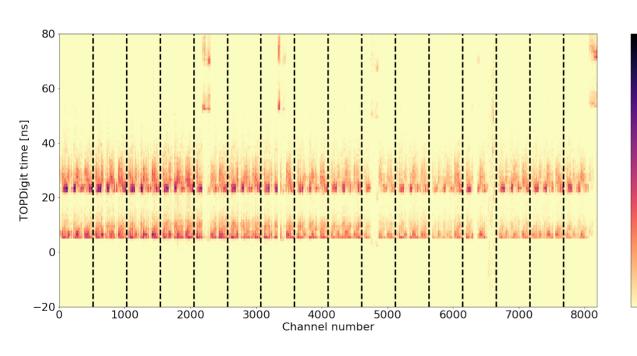
Channel synchronization in collision events

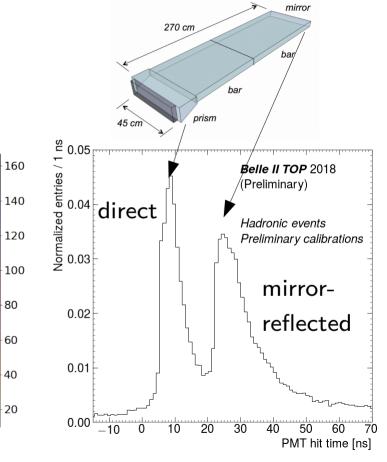




Very first test of the calibrations:

- \rightarrow All the 8192 channels are aligned correctly
- → Clear distinction of direct and reflected light





-80

60

40

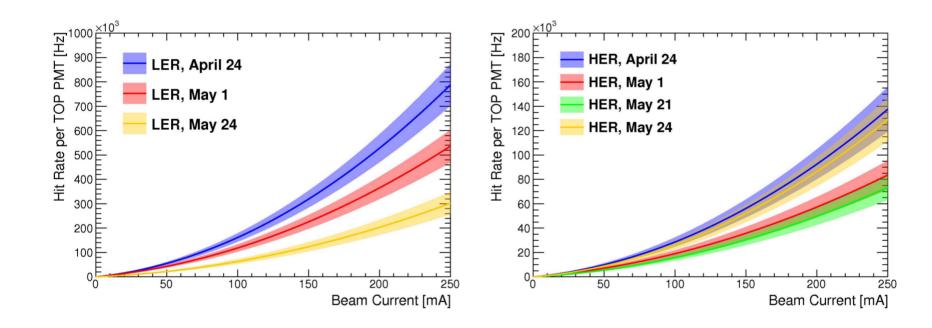
20

TOP as a background monitor





- From separate LER/HER current scans
- Showing average of all fits (>90% of channels give good fits)



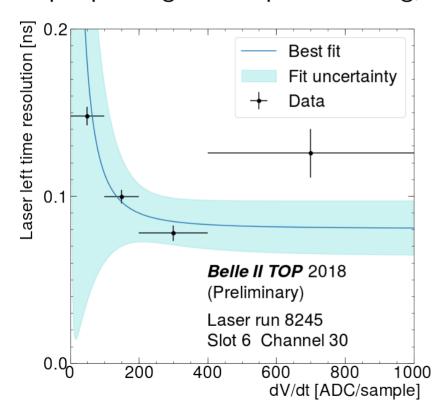
The TOP is an excellent background detector

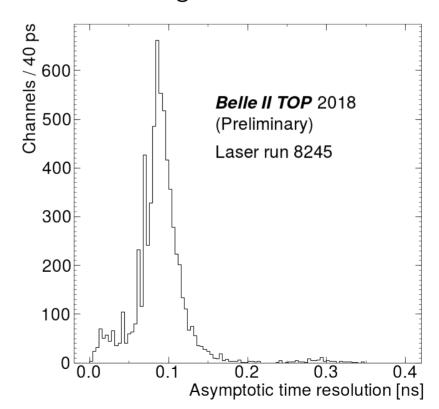
Asymptotic resolution





The timing has a quite strong dependence on the slope of the hit rising edge (dV/dt). Steeper pulses get more precise timing, since the noise term gets smaller



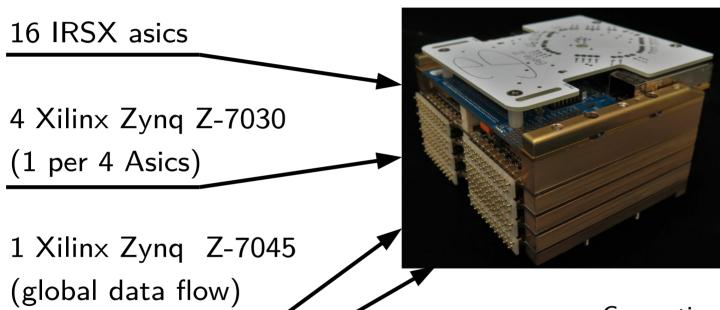


1 HV board





Each module is read by 64 ASICs packed into 4 boardstacks



Computing power used mostly for

- → Online pedestal subtraction
- → Online waveform analysis

See Maeda-san's poster for more information!